

Intersections with a Sphere

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[-] A Plane and a Sphere

Define a plane and a sphere:

restart

$eq1 := p + q + r = 1$

$eq2 := p^2 + q^2 + r^2 = 1$

Plot them, along with the projections of their intersection.

with(plots)

with(plottools)

$P := \text{implicitplot3d}(eq1, p = -1.2 .. 1.2, q = -1.2 .. 1.2, r = -1.2 .. 1.2, \text{style} = \text{patchnogrid}, \text{color} = \text{gold})$

$S := \text{implicitplot3d}(eq2, p = -1.2 .. 1.2, q = -1.2 .. 1.2, r = -1.2 .. 1.2, \text{style} = \text{patchcontour}, \text{grid} = [20, 20, 20], \text{color} = \text{blue})$

$\text{varlist} := [p, q, r]$

for j **in** varlist **do**

$eq_j := \text{op}(\text{eliminate}(\{eq1, eq2\}, j))$

$x := \text{remove}(\text{has}, \text{varlist}, j)$

$y := \text{remove}(\text{has}, \text{varlist}, j)$

$C_j := \text{implicitplot}(eq_j, x = -1.2 .. 1.2, y = -1.2 .. 1.2, \text{color} = \text{red}, \text{thickness} = 2)$

od

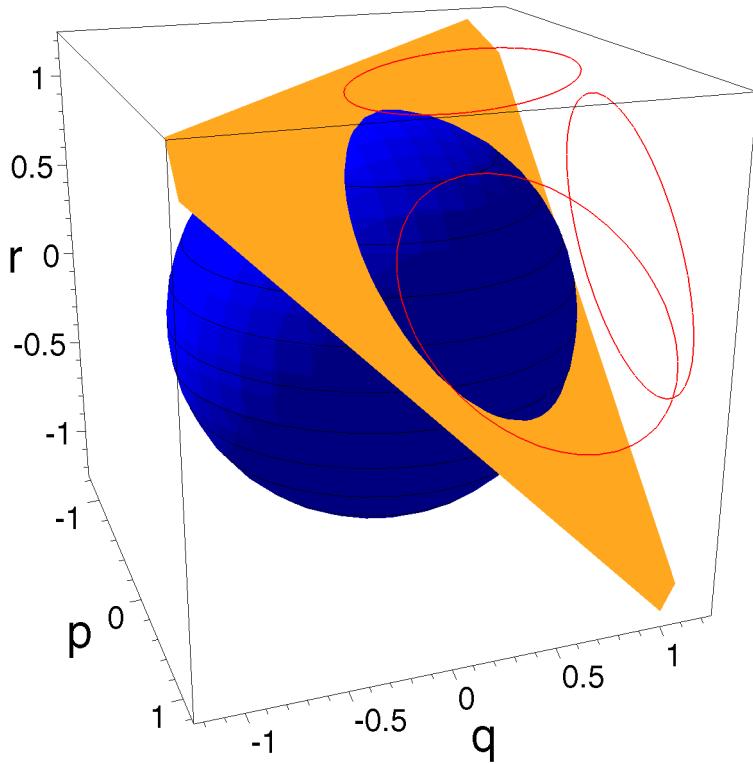
$f_p := \text{transform}((x, y) \rightarrow [1.2, x, y])$

$f_q := \text{transform}((x, y) \rightarrow [x, 1.2, y])$

$f_r := \text{transform}((x, y) \rightarrow [x, y, 1.2])$

$\text{display}(P, S, \text{seq}(f_.(\text{op}(i, \text{varlist}))(C_.(\text{op}(i, \text{varlist}))), i = 1 .. 3), \text{orientation} = [-20, 70],$

```
labels = [ "p", "q", "r" ], scaling = constrained, lightmodel = light2 )
```



- The Projection of the Intersection is an Ellipse

- One Ellipse

The explicit solutions for (p,q) , parametrized by r , of the intersection curve are

```
[ allvalues( solve( { eq1, eq2 }, { p, q } )) ]
```

$$\left[\{ q = -\frac{1}{2}r + \frac{1}{2} + \frac{1}{2}\sqrt{-3r^2 + 2r + 1}, p = -\frac{1}{2}r + \frac{1}{2} - \frac{1}{2}\sqrt{-3r^2 + 2r + 1} \}, \right.$$

$$\left. \{ q = -\frac{1}{2}r + \frac{1}{2} - \frac{1}{2}\sqrt{-3r^2 + 2r + 1}, p = -\frac{1}{2}r + \frac{1}{2} + \frac{1}{2}\sqrt{-3r^2 + 2r + 1} \} \right]$$

p and q are interchangeable. Plot both sets:

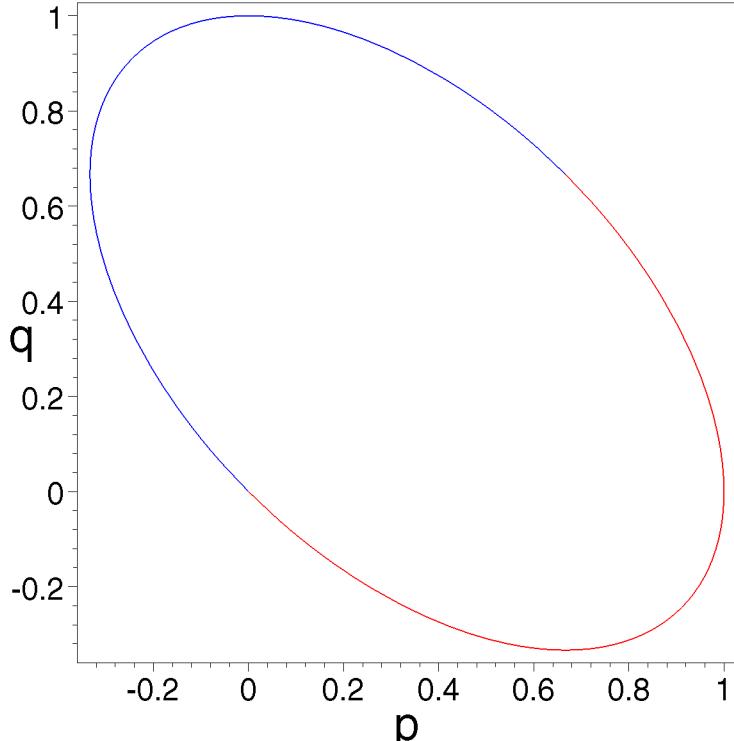
```
sols1 := [ rhs( op( select( has, %_1, p ))), rhs( op( select( has, %_1, q )))]
```

```
sols2 := [ rhs( op( select( has, %%_2, p ))), rhs( op( select( has, %%_2, q )))]
```

```

sols1 := [ - $\frac{1}{2}r + \frac{1}{2} - \frac{1}{2}\sqrt{-3r^2 + 2r + 1}$ ,  $-\frac{1}{2}r + \frac{1}{2} + \frac{1}{2}\sqrt{-3r^2 + 2r + 1}$  ]
sols2 := [ - $\frac{1}{2}r + \frac{1}{2} + \frac{1}{2}\sqrt{-3r^2 + 2r + 1}$ ,  $-\frac{1}{2}r + \frac{1}{2} - \frac{1}{2}\sqrt{-3r^2 + 2r + 1}$  ]
[solve(select(has, sols1, r^2), r)]
[ $\frac{-1}{3}, 1$ ]
plot([op(sols1), r = %1 .. %2], [op(sols2), r = %1 .. %2]), scaling = constrained,
color = [blue, red], thickness = 2, labels = ["p", "q"])

```



This is, of course, just the ellipse that is the plane-sphere intersection projected onto the (p,q) plane.

- Another Ellipse

Let's look at the intersection parametrized by (p,q) .

`eliminate({ eq1, eq2 }, r)`

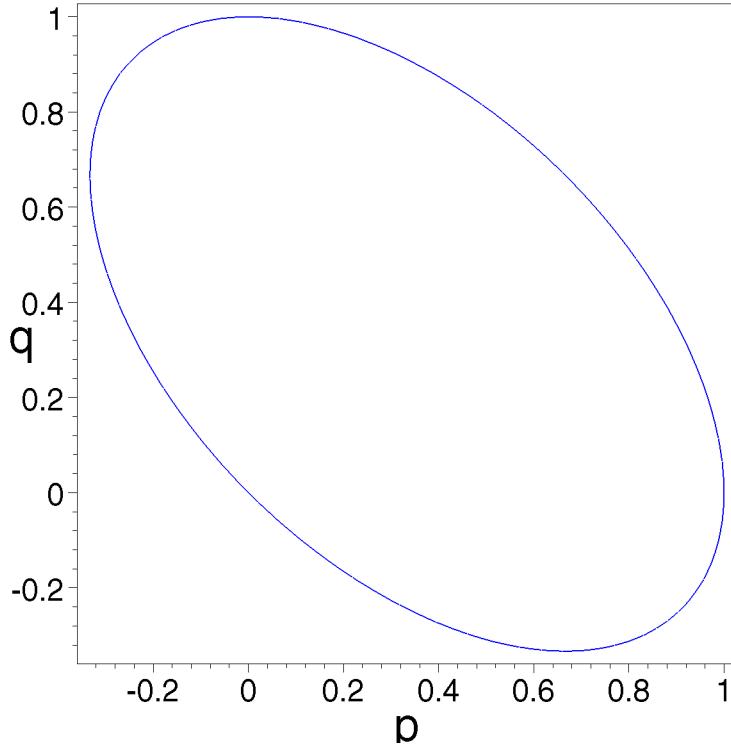
`[{ r = -p - q + 1 }, { p^2 + q^2 + p q - p - q }]`

`pq := op(%2) = 0`

$$pq := p^2 + q^2 + p q - p - q = 0$$

which is an equation for an ellipse. Plotting this equation implicitly produces the same ellipse as above.

```
implicitplot(pq, p = -1 .. 1, q = -1 .. 1, grid = [50, 50], scaling = constrained, color = blue,
thickness = 2)
```



Ellipses the Pun ...

We can remove the cross term with a rotation:

```
pqsubs := [p = u cos(theta) - v sin(theta), q = u sin(theta) + v cos(theta)]
```

```
subs(pqsubs, pq)
```

```
collect(%, [u, v], combine, distributed)
```

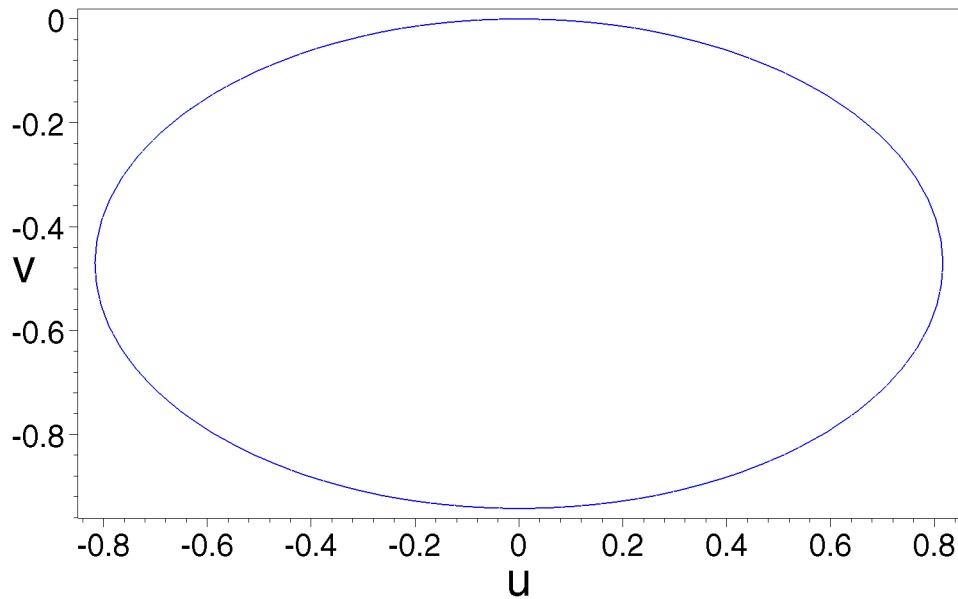
$$\left(1 + \frac{1}{2} \sin(2\theta)\right)u^2 + \cos(2\theta)v u + (-\cos(\theta) - \sin(\theta))u + (\sin(\theta) - \cos(\theta))v \\ + \left(-\frac{1}{2} \sin(2\theta) + 1\right)v^2 = 0$$

```
eval(subs(theta = 3pi/4, %))
```

$$\frac{1}{2}u^2 + \sqrt{2}v + \frac{3}{2}v^2 = 0$$

```
uv := %
```

```
implicitplot(uv, u = -1 .. 1, v = -1 .. 1, grid = [ 50, 50 ], scaling = constrained, color = blue,  
thickness = 2 )
```



We can easily put the equation into standard form:

```
csquare(uv, v)
```

$$\frac{3}{2} \left(v + \frac{1}{3} \sqrt{2} \right)^2 + \frac{1}{2} u^2 - \frac{1}{3} = 0$$

```
map(x → 3 x + 1, %)
```

$$\frac{9}{2} \left(v + \frac{1}{3} \sqrt{2} \right)^2 + \frac{3}{2} u^2 = 1$$

[-] An Interesting Surface

Recall the sphere and plane equations:

```
eq1
```

```
eq2
```

$$p + q + r = 1$$

$$p^2 + q^2 + r^2 = 1$$

Now, consider $\text{map}(x \rightarrow x^2, eq1)$

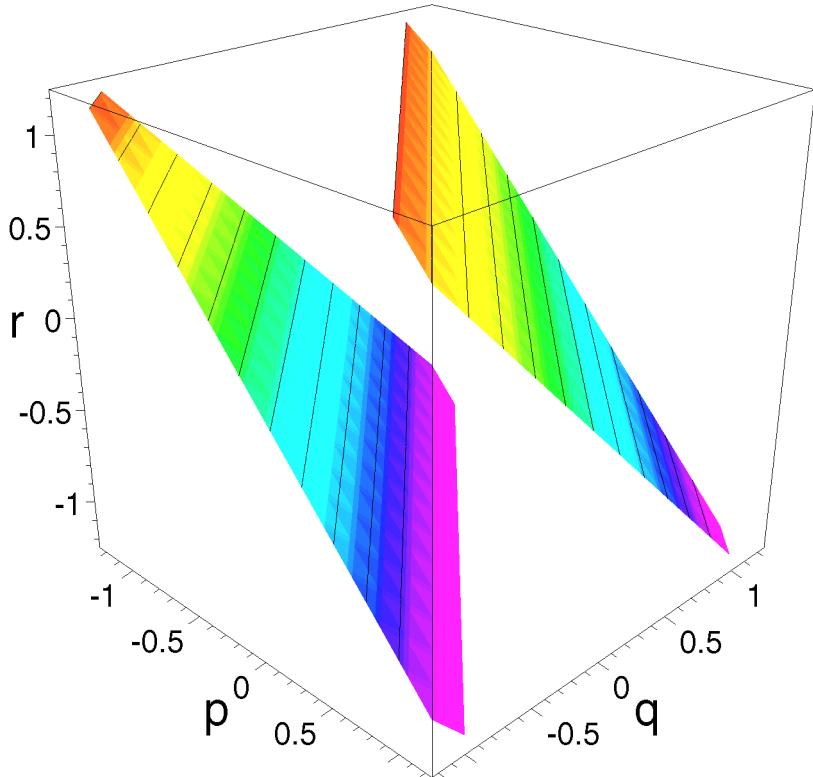
$$(p + q + r)^2 = 1$$

$eqQ := %$

This is a quadratic surface whose appearance is

```
Q := implicitplot3d(eqQ, p = -1.2 .. 1.2, q = -1.2 .. 1.2, r = -1.2 .. 1.2, style = patchcontour,
grid = [15, 15, 15])
```

```
display(Q, labels = ["p", "q", "r"], orientation = [-45, 65], scaling = constrained)
```



We've doubled our plane. Substitute the sphere equation into this to get

$\text{simplify}(eqQ, \{ eq2 \})$

$$2 p q + 2 p r + 2 q r + 1 = 1$$

$$\text{map}\left(x \rightarrow \frac{x - 1}{2}, \% \right)$$

$$p q + p r + q r = 0$$

$eq3 := %$

Another way to view this is $\text{isolate}(eq3, r)$

$$r = -\frac{pq}{p+q}$$

eq_r := rhs(%)

So we have a hyperboloid. A plot of this equation is

$$rvals := \left[\text{seq}\left(-1.2 + \frac{i \cdot 2.4}{16}, i = 1 .. 16 \right) \right]$$

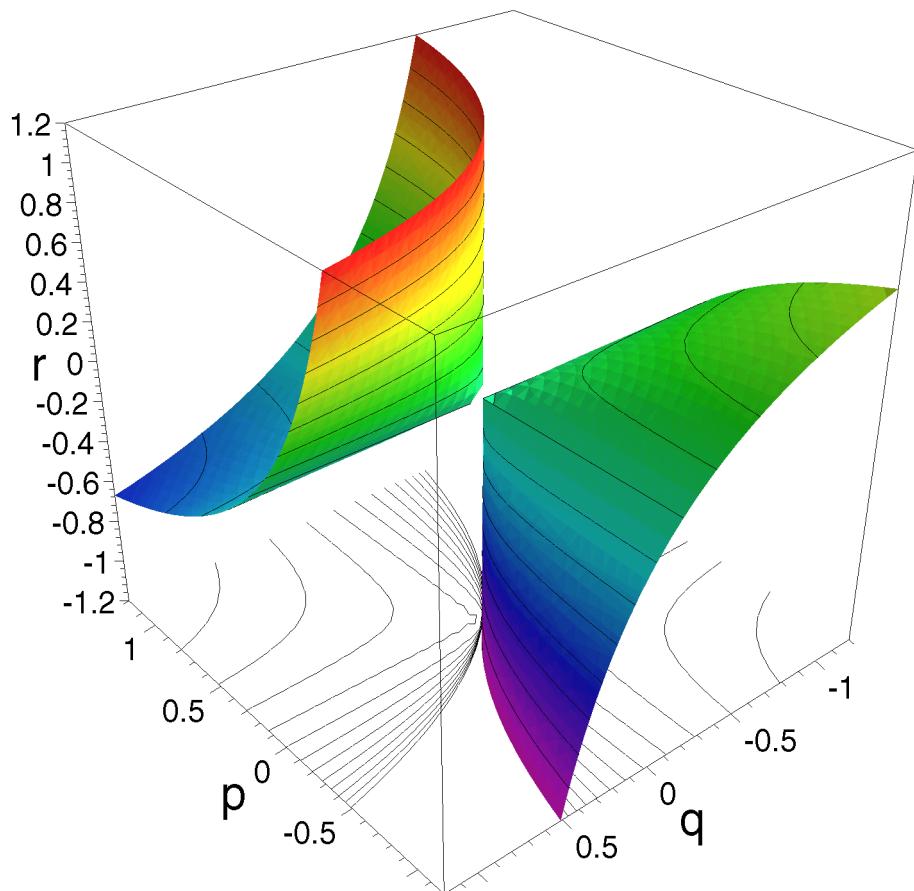
for *i* **to** 16 **do** *c.i* := implicitplot(subs(*r* = op(*i*, *rvvals*), *eq3*), *p* = -1.2 .. 1.2, *q* = -1.2 .. 1.2,
scaling = constrained, color = black)

od

f := transform((*x*, *y*) → [*x*, *y*, -1.2])

H := implicitplot3d(*eq3*, *p* = -1.2 .. 1.2, *q* = -1.2 .. 1.2, *r* = -1.2 .. 1.2, style = patchcontour,
grid = [35, 35, 35], contours = *rvvals*)

display(seq(*f*(*c.i*), *i* = 1 .. 16), *H*, labels = ["p", "q", "r"], orientation = [140, 60],
view = [-1.2 .. 1.2, -1.2 .. 1.2, -1.2 .. 1.2])



Let's put this in standard form. First, rotate in the (*q*, *r*) plane.

```

[ qrsubs := [ q = u cos(θ) - v sin(θ), r = u sin(θ) + v cos(θ) ]
[ subs(qrsubs, eq3)
[ collect(%o, [ u, v ], combine, distributed)

$$\frac{1}{2} \sin(2\theta) u^2 + \cos(2\theta) v u + (p \cos(\theta) + p \sin(\theta)) u + (-p \sin(\theta) + p \cos(\theta)) v$$


$$-\frac{1}{2} \sin(2\theta) v^2 = 0$$

[ eval(subs(θ =  $\frac{3\pi}{4}$ , %o))

$$-u^2 - 2p\sqrt{2}v + v^2 = 0$$

[ Next, rotate in the (p,v) plane.
[ pvsups := [ p = s cos(θ) - t sin(θ), v = s sin(θ) + t cos(θ) ]
[ collect(subs(pvsups, %%), [ s, t ], combine, distributed)

$$\left(-\sqrt{2} \sin(2\theta) + \frac{1}{2} - \frac{1}{2} \cos(2\theta)\right) s^2 + (-2\sqrt{2} \cos(2\theta) + \sin(2\theta)) t s$$


$$+ \left(\sqrt{2} \sin(2\theta) + \frac{1}{2} \cos(2\theta) + \frac{1}{2}\right) t^2 - u^2 = 0$$

[ isolate(remove(has, lhs(%o), { s^2, t^2, u^2 }), θ)

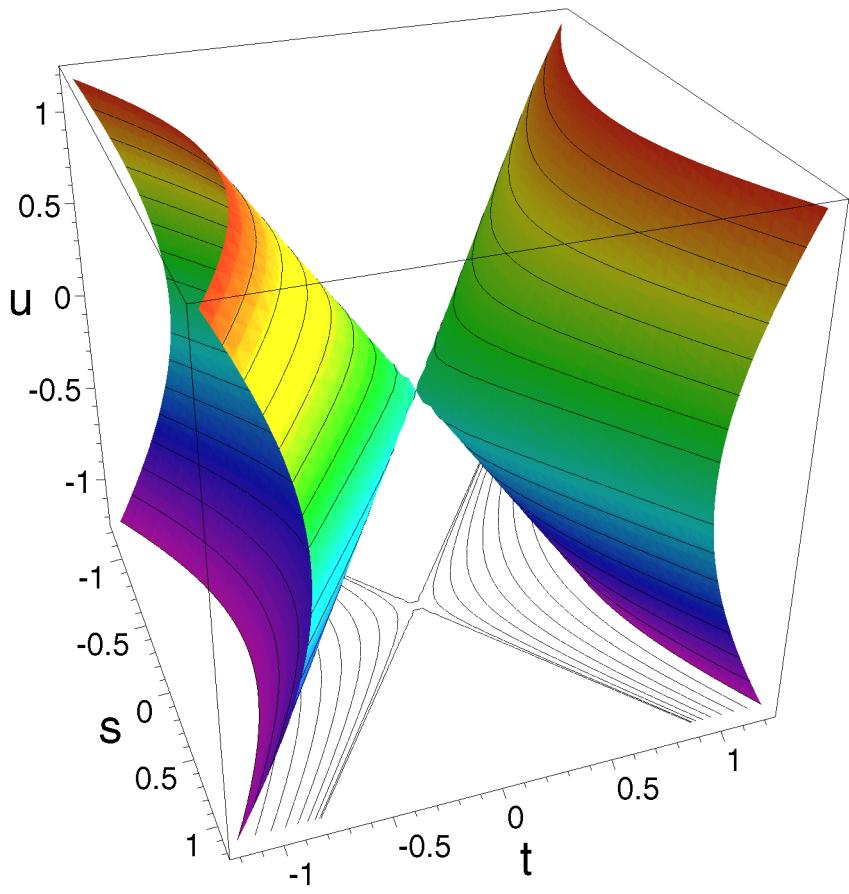
$$\theta = \frac{1}{2} \arctan(2\sqrt{2})$$

[ eval(subs(%o, %%))

$$-s^2 + 2t^2 - u^2 = 0$$

[ stu := %
[ Much better. Plot this:
[ stu_plot := implicitplot3d(stu, s = -1.2 .. 1.2, t = -1.2 .. 1.2, u = -1.2 .. 1.2, style = patchcontour,
  grid = [ 35, 35, 35 ], contours = rvals)
[ for i to 16 do c.i := implicitplot(subs(u = op(i, rvals), stu), s = -1.2 .. 1.2, t = -1.2 .. 1.2,
  scaling = constrained, color = black, grid = [ 50, 50 ])
[ od
[ display(seq(f(c.i), i = 1 .. 16), stu_plot, labels = [ "s", "t", "u" ], orientation = [ -20, 60 ],
  scaling = constrained)

```



```
[read "c:/Maple/SpherePlane.m"
 [save "c:/Maple/SpherePlane.m"
 [?
```